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The following sections provide a brief description of NavCad's capabilities and a guide to the NavCad API. The documentation available online[*1] (should answer most questions. For a detailed overview of the API, refer to the API reference (API [#sec:API] --- NavCad's API consists of a series of C#.NET interfaces for interfacing with NavCad's OSC API. The API supports the following primary functions: - Connection management - Navigation and waypoint management - Shipment management - Waypoint and vessel waypoint model calculation - Time based calculations - Wave data manipulation NavCad also has a number of open source Visual Studio projects that demonstrate additional functionality, including all of the waypoints and wave models available in NavCad, the NavCad API and samples of how to use the NavCad API in combination with the OSC API. These can be found at [github.com/navcad/navcad/] and the [navcad.org](website. Hydrodynamic Model [#sec:Hydro] ----- The NavCad hydrodynamic model is set up to deal with waves in 1D. However, due to the computational complexity of full wave models in 1D, NavCad's hydrodynamic model is set up to deal with waves in a 2D or 3D region. NavCad includes a 2D and 3D wave model that can be used for both open ocean, coastal, and narrowband simulations. NavCad ships with two open ocean wave models that use the MITT[MIT] or NREL[NREL] wave models, which can be used in conjunction with NavCad for open ocean simulations. The NavCad hydrodynamic model supports the following 1D wave parameters: frequency, wind direction, wave height, wave steepness, period, and wave duration. However, the NavCad hydrodynamic model does not support the following 1D wave parameters: amplitude, phase and wavelength. For additional information on how to set up a 1D simulation 82157476af

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